

Particle Event Generation using Generative Adversarial Networks (GANs)

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The SoLid Experiment

- Sterile neutrinos are a hypothesised neutrino flavour which do not interact via the weak force [1].
- SoLid is a neutrino detector constructed next to a nuclear reactor. It searches for antineutrinos via inverse beta decay [2].
- Comprised of thousands of individual detection cubes.
- Background sources need to be removed from the dataset.
- Atmospheric muons are easily identified within the detector, and this data is cut from the dataset. However, these muons can scatter neutrons which may enter the detector volume.

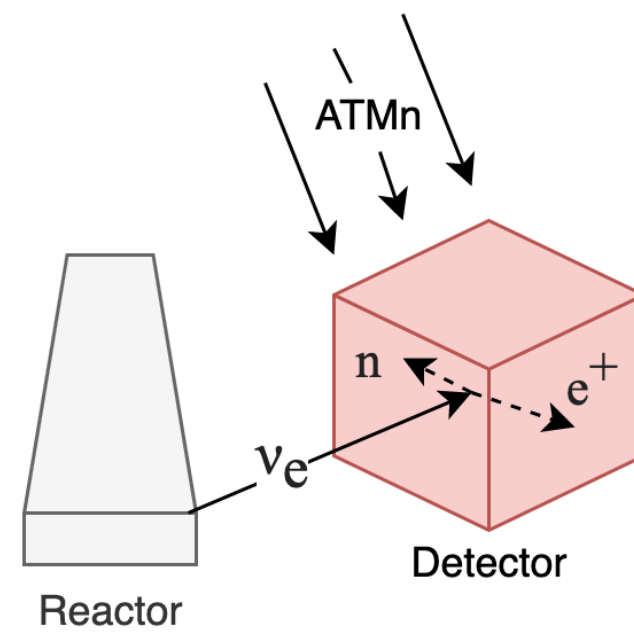


Figure 1: Basic Operation of the SoLid detector.

Research Aims

- Build a Generative Adversarial Network (GAN) for efficient simulation of ATMn events.
- Develop methods to investigate the capabilities of a 2D GAN for the production of 3D data.
- Use data augmentation techniques to improve Signal/Background classification at SoLid.

Atmospheric Neutron Events

- Neutrons scatter electrons along their path which deposit energy in the detector cubes.
- The dataset consists of real events from the detector alongside Monte Carlo simulated events.
- Datasets built from orthogonal projections of each event; produced by summing over each coordinate axis.

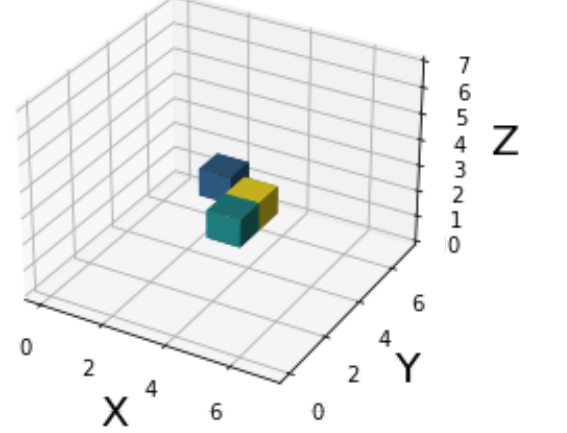


Figure 2: An ATMn event.

Generative Adversarial Networks

- Generative Adversarial Networks (GANs) typically consist of two neural networks: Discriminator and Generator.
- GAN simulation is very computationally inexpensive.
- A Discriminator classifies whether input data is real or generated. The Generator converts an input noise vector into an event.
- They compete with each other in a Zero-sum game [3]:
$$\min_G \max_D V(D, G) = \mathbb{E}_{x \sim p_{\text{data}}(x)} [\log D(x)] + \mathbb{E}_{z \sim p_z(z)} [\log (1 - D(G(z)))]$$
- Implemented a 2D DCGAN where the generator uses transposed convolutions and the discriminator is a convolutional neural network (CNN).

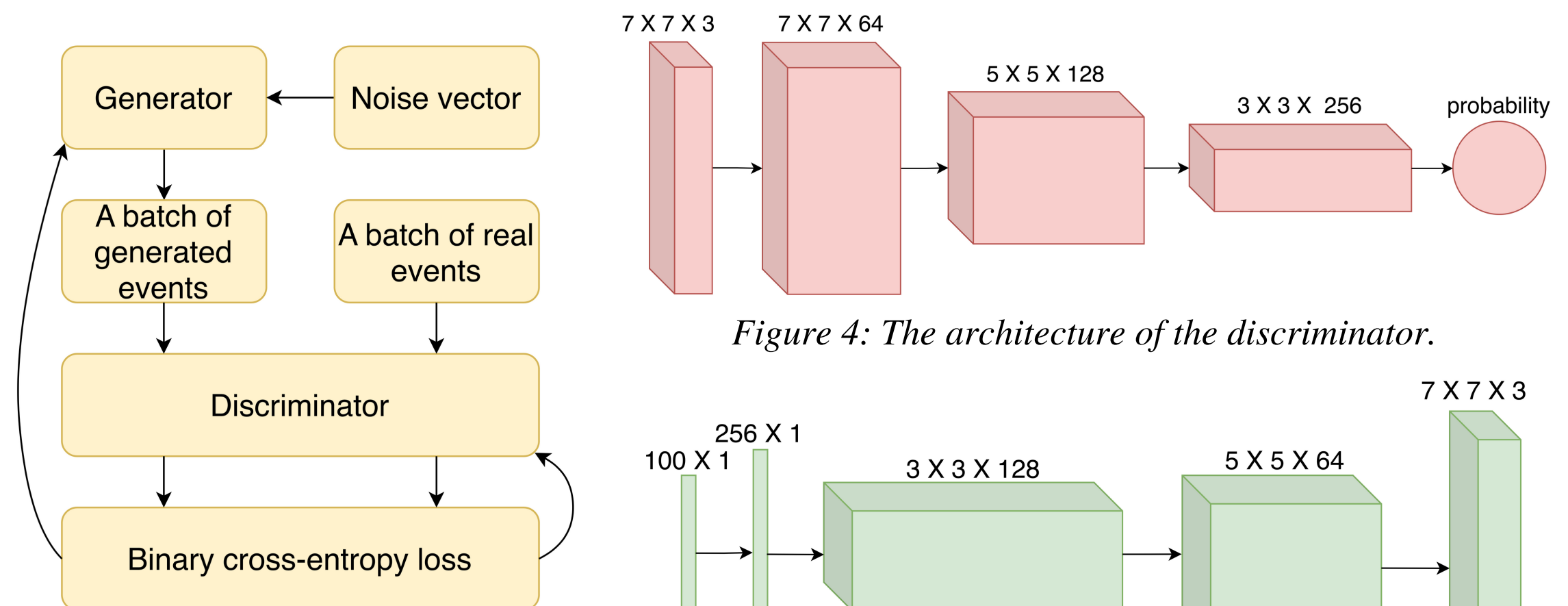


Figure 3: Adapted from [4]. A flow chart of the training process.

Figure 4: The architecture of the discriminator.

Figure 5: The architecture of the generator.

Results

- Generated events can be compared by eye to real events.

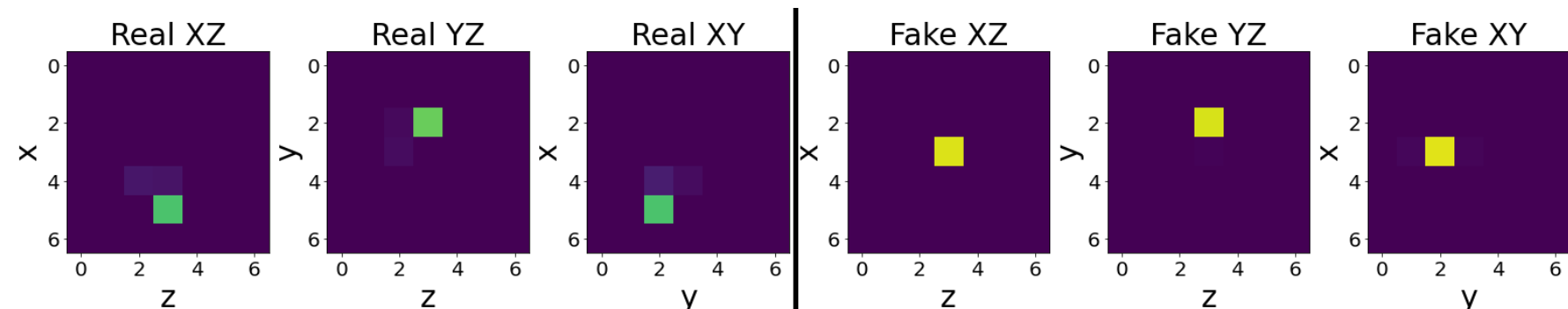


Figure 6: A real event and a fake event displayed for visual comparison. Brighter pixels represent higher energy.

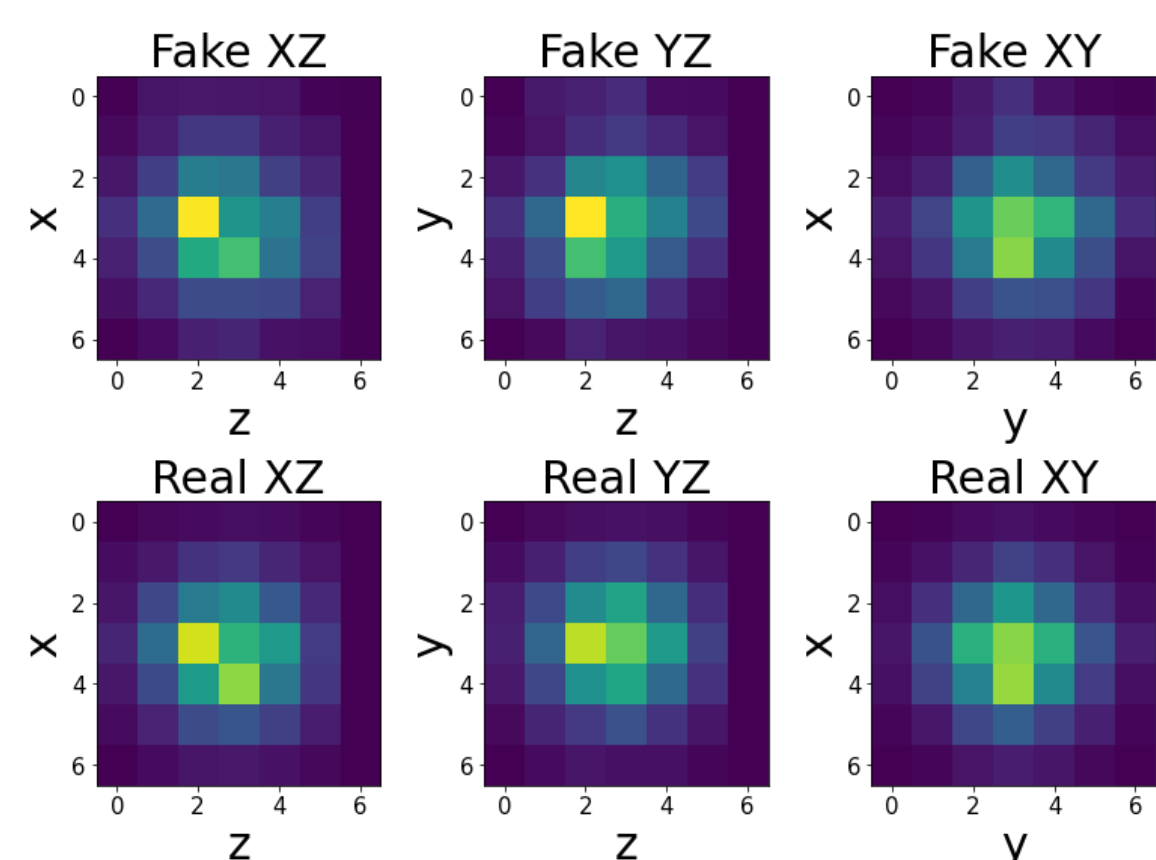


Figure 7: Average images produced from the fake and real dataset.

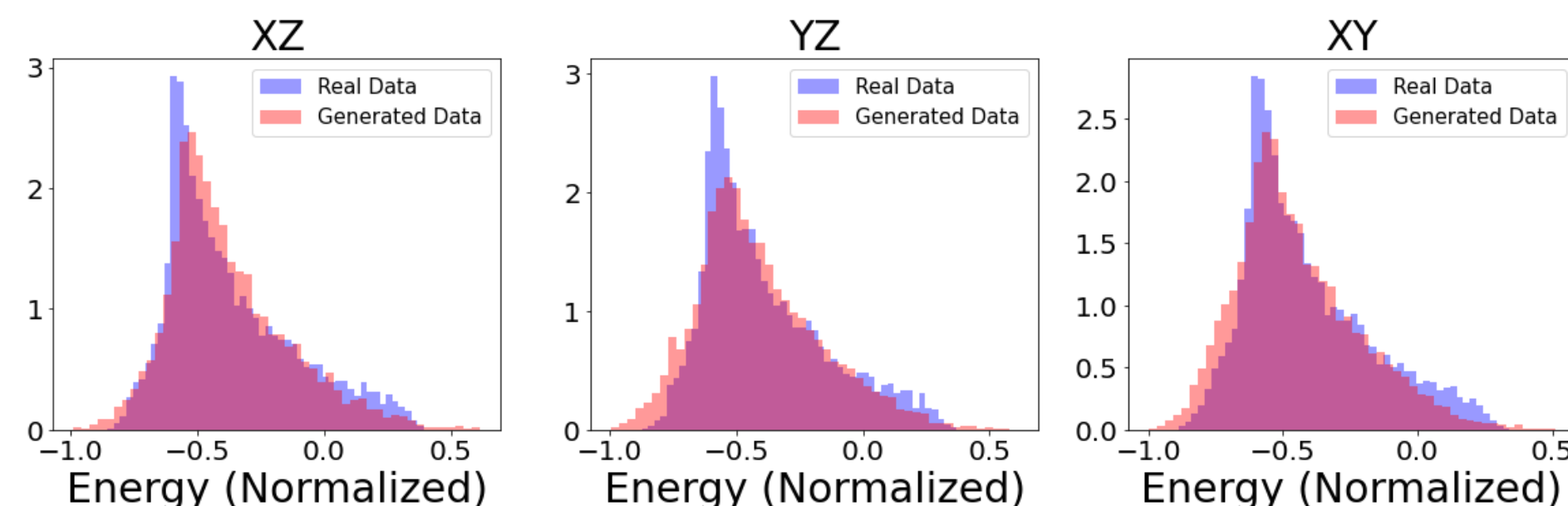


Figure 8: Distributions of maximum energy in each plane.

- The average of the dataset for each plane can be compared.
- These scores are a general measure, a GAN should be able to learn specific features within events.
- A key feature is the energy distribution of the maximum pixels.

Can a 2D GAN learn 3D Space?

- Similar averages of cross-plane correlations suggest 3D space has been learnt.
- A CNN was trained to establish the probability of a generated event existing in real space.
- The training data is real correlation planes, shuffling to create fake data.

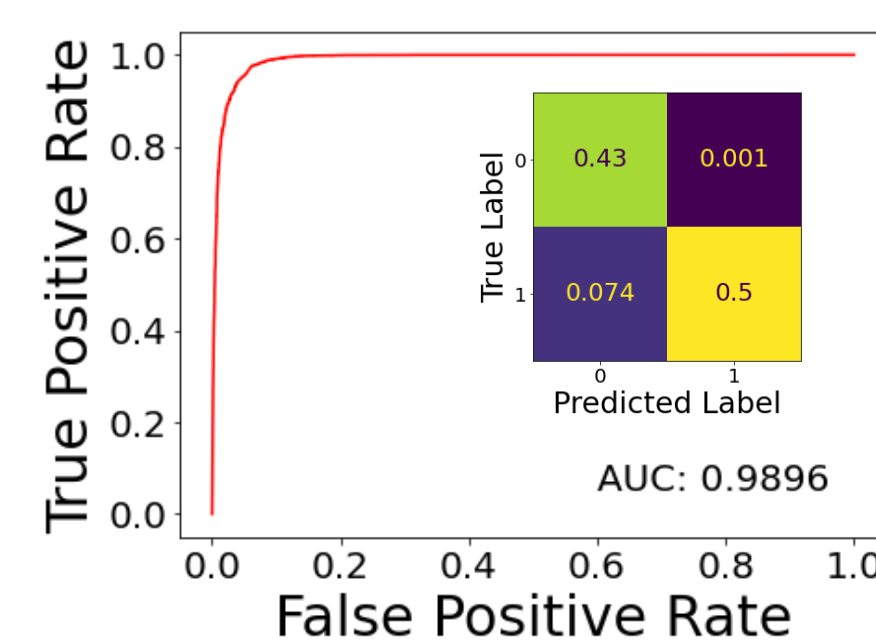


Figure 10: Confusion matrix (inset) and ROC curve for the trained CNN.

- High, convergent output of CNN as GAN trains gives confidence that images are 3D events.
- Initial output is 1; Random noise looks correlated to the CNN.
- Standard deviation of CNN predictions falls over time.

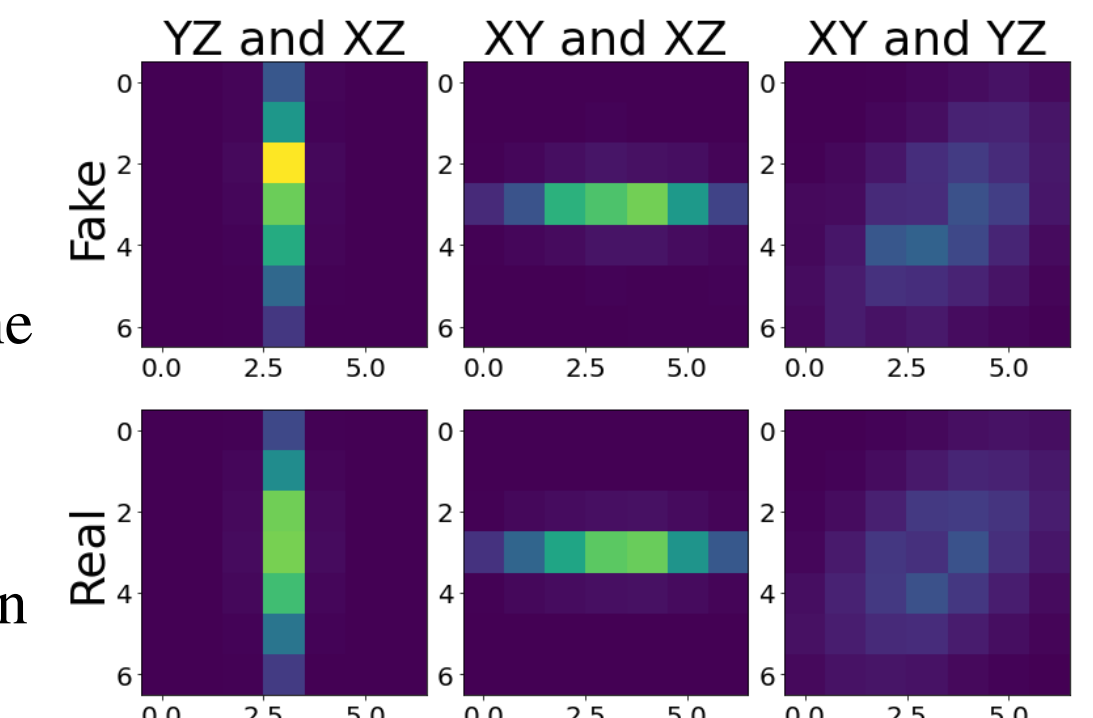


Figure 9: Average 2D correlations of the planes.

- An ideal classifier performance yields a diagonal matrix.
- The area under a ROC curve (AUC) is 1 for an ideal classifier [5].
- Other types of background are classified as real with high probability; CNN identifies 3D features which are irrespective of the background type.

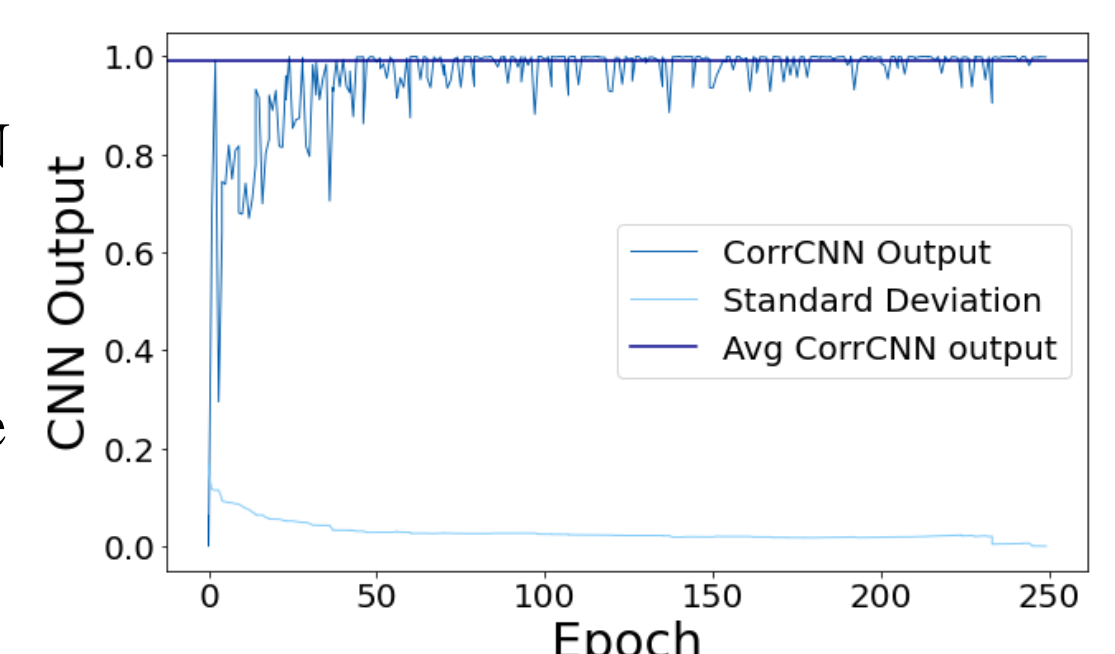


Figure 11: CNN output during GAN training.

Conclusions

- The GAN's performance can be evaluated by visual metrics, such as comparing events, average planes and energy distribution.
- An additional CNN is able to explicitly demonstrate that the 2D GAN is capable of learning 3D space events.

Future Investigations

- The CNN outputs can be used within the GAN training to constrain the training; this may help it to learn the 3D correlations quicker.
- A HybridGAN could be implemented to produce additional variables alongside the image planes.